# A graphic explanation of Red-black trees

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### Red-black trees

A red-black tree is

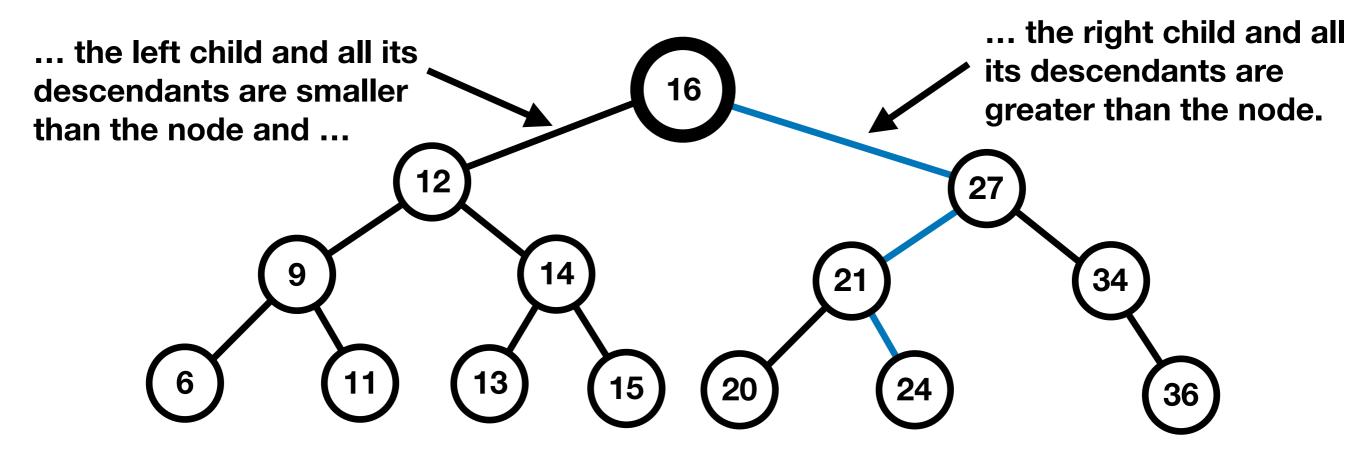
one of the easiest and most important self-balancing binary search trees.

(implemented by, e.g., C++'s std::map, Java's TreeMap)

### Binary search trees

#### Each node has:

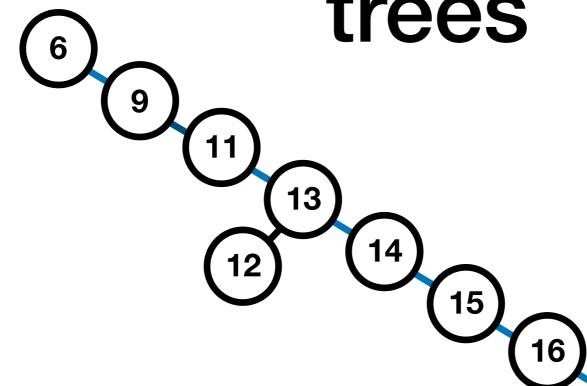
- some orderable piece of data (key), say a number
- can have a left child and
- can have a right child such that ...



Tree "balanced": fast look-ups, e.g., if tree had 1 million nodes, only traverse 20.

Similar to opening a phone book or dictionary in the middle and deciding whether to continue searching in the left or right half.

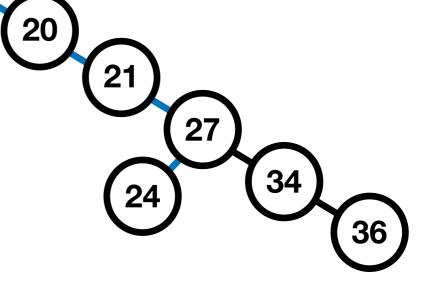
## Unbalanced binary search trees



**However:** 

"unbalanced tree": look-ups just as slow as a brute force search.

Red-black tree = binary search tree with one extra bit of information per node (the color "red" or "black") that obey certain rules so that they never become unbalanced, no matter in what order the elements were inserted when creating the tree.



## A graphic way to think about red-black trees

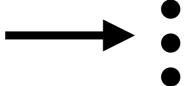
A red-black tree is a tree drawn on red ruled paper obeying certain rules.

## Draw tree on red ruled paper

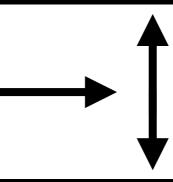
But drawing all the red zones in red actually hurts the eyes too much, so just imagine it.

### Draw tree on ruled paper

"Black" gridlines extend indefinitely to the top.



All the zones between two gridlines or below the lowest gridline are "red".

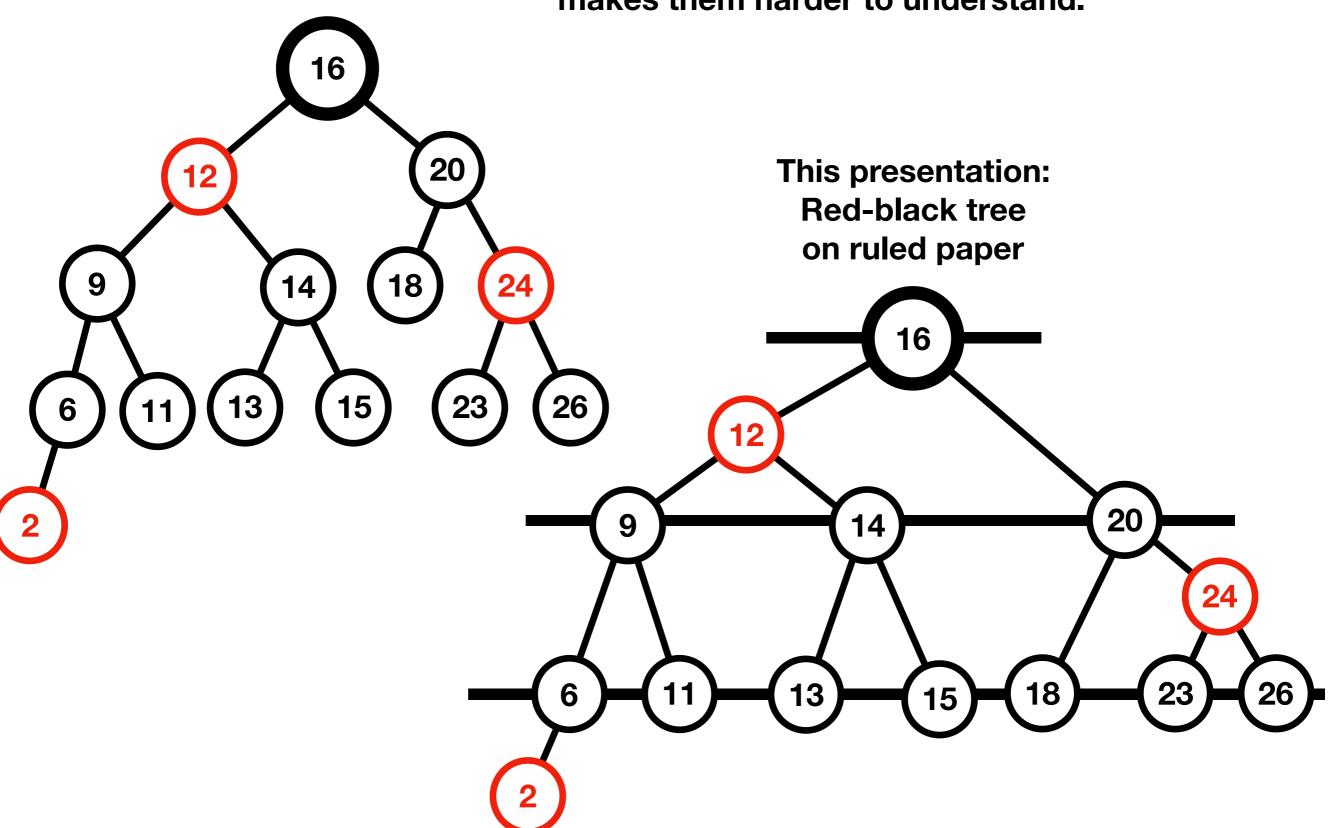


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But there is a lowest gridline.

Traditional textbook:
Red-black tree
as colored tree

Unfortunately, most traditional textbooks do not draw red-black trees on ruled paper - which makes them harder to understand.



### The rules

#### The rules for red-black trees now become:

(compare to, e.g., Cormen et al "Introduction to Algorithms")

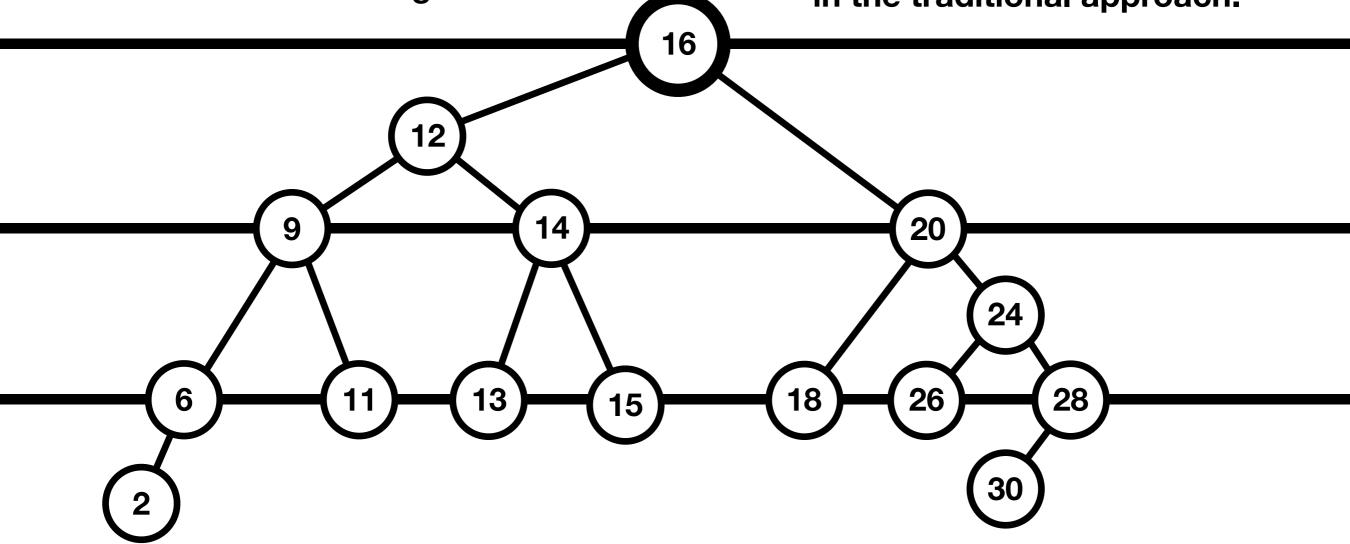
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Each node is considered to be either

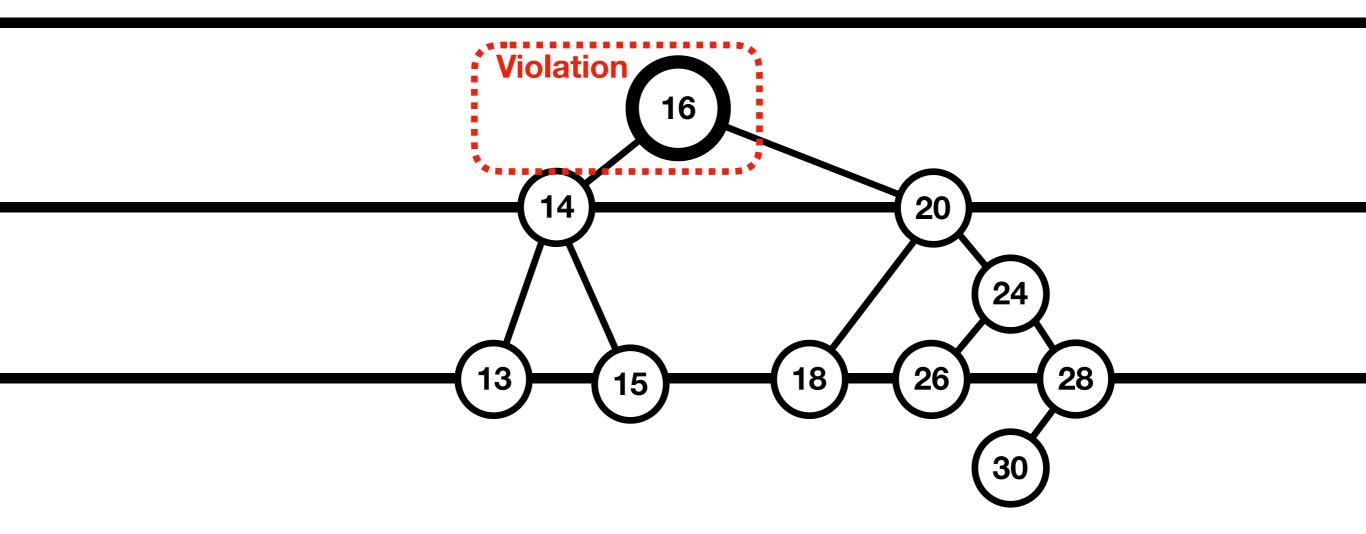
on a black gridline or

in a red zone between gridlines.

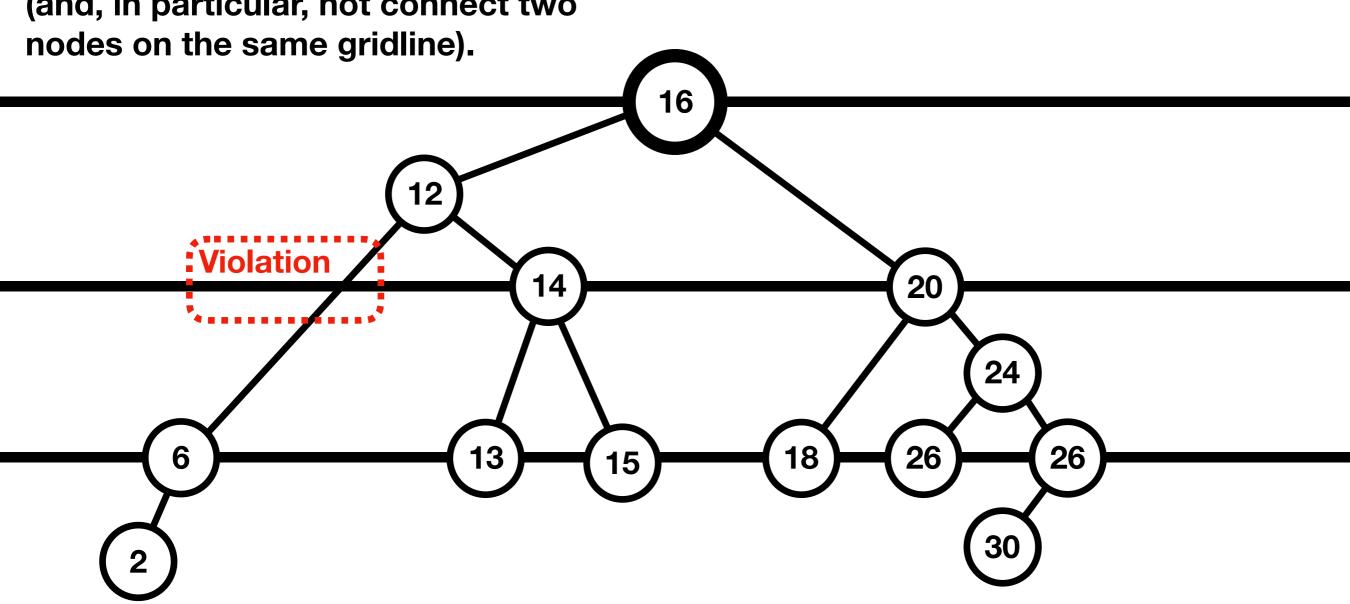
This corresponds to the node being colored "black" or "red" in the traditional approach.



The root has to be on a gridline.

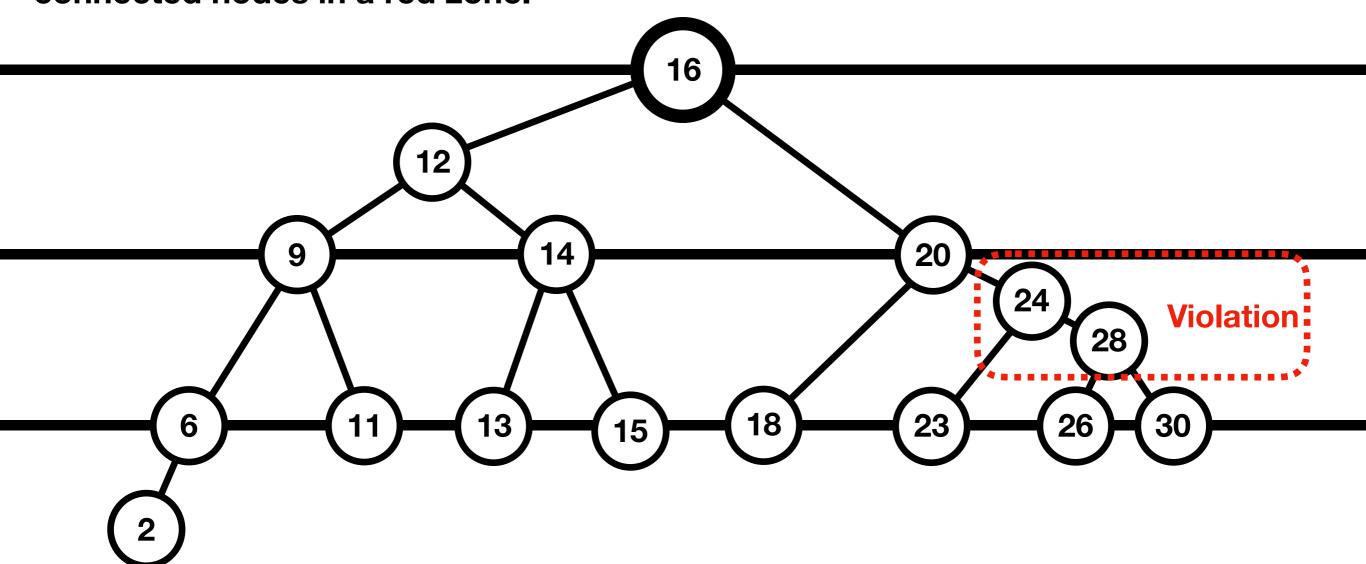


An edge cannot cross a gridline (and, in particular, not connect two



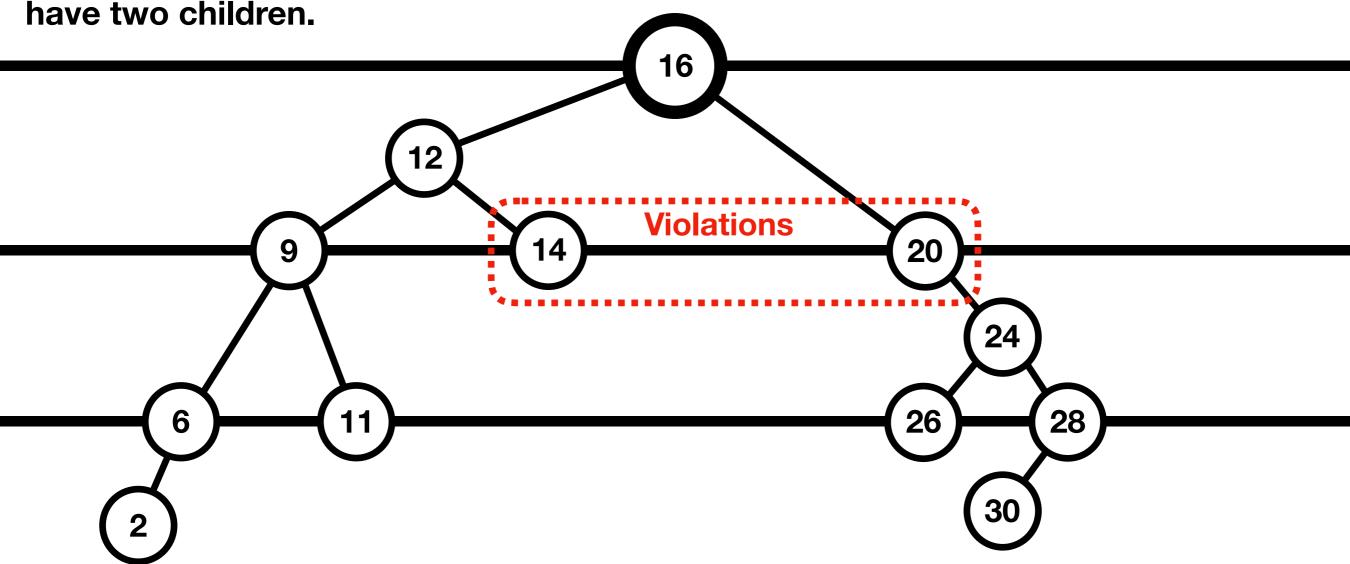
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There cannot be two or more connected nodes in a red zone.



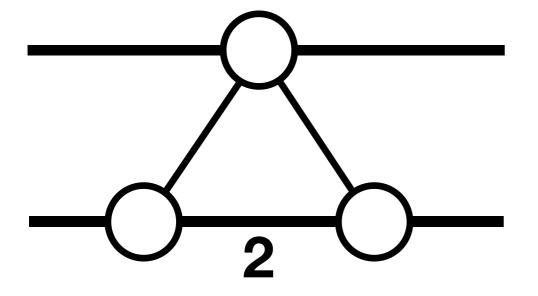


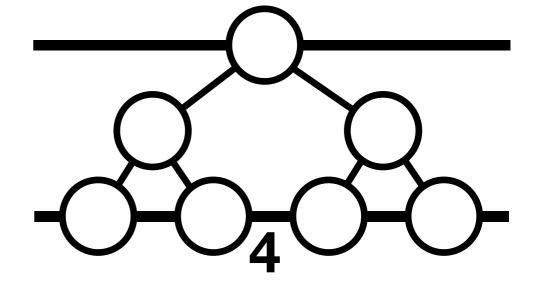
Each node not on or below the lowest gridline must have two children.



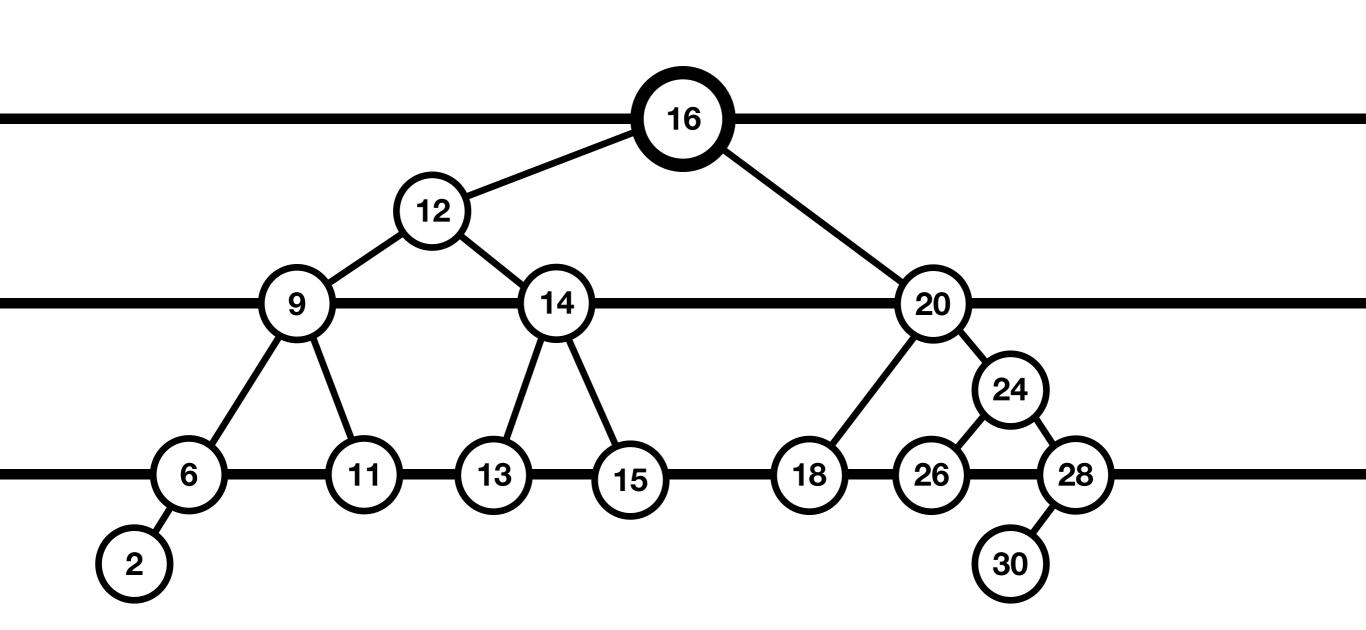
### Search time

The rules enforce that (starting from the root), for each gridline down, the number of nodes doubles to quadruples, so the tree grows *exponentially*:



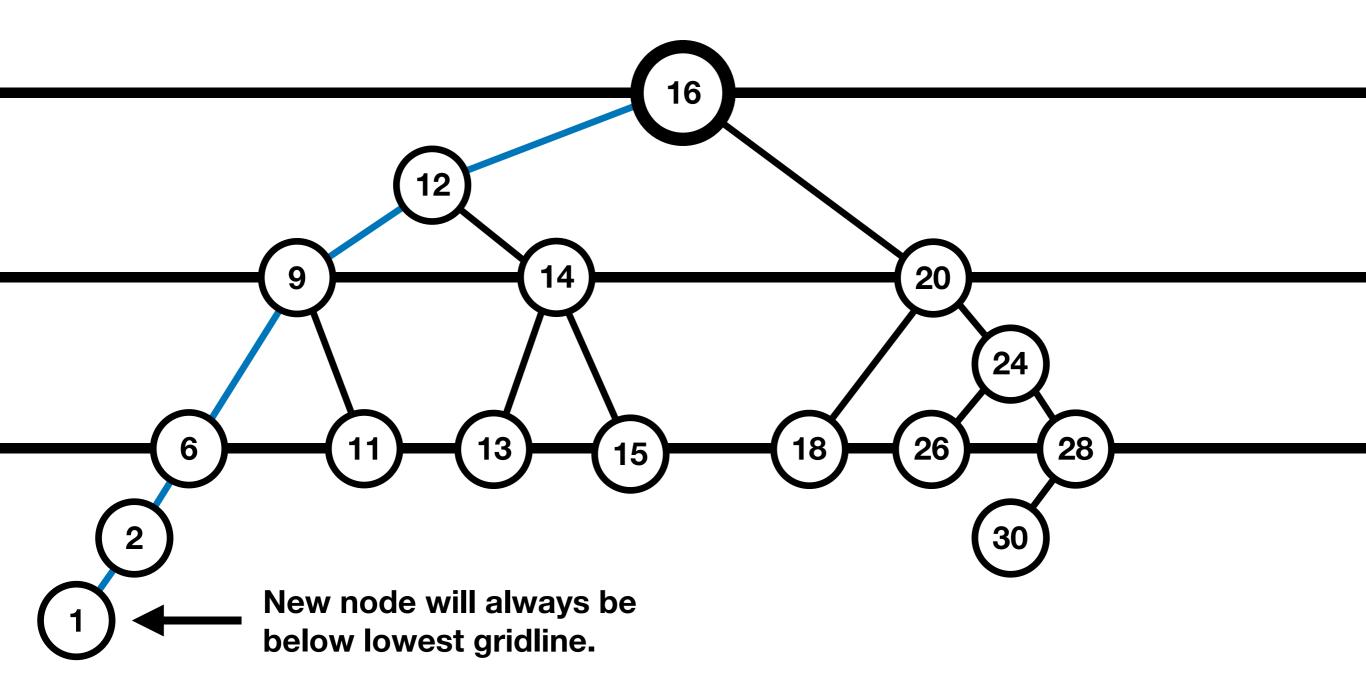


Thus, the number of gridlines occupied by the tree and, hence, the search time grows logarithmically in the number of nodes.



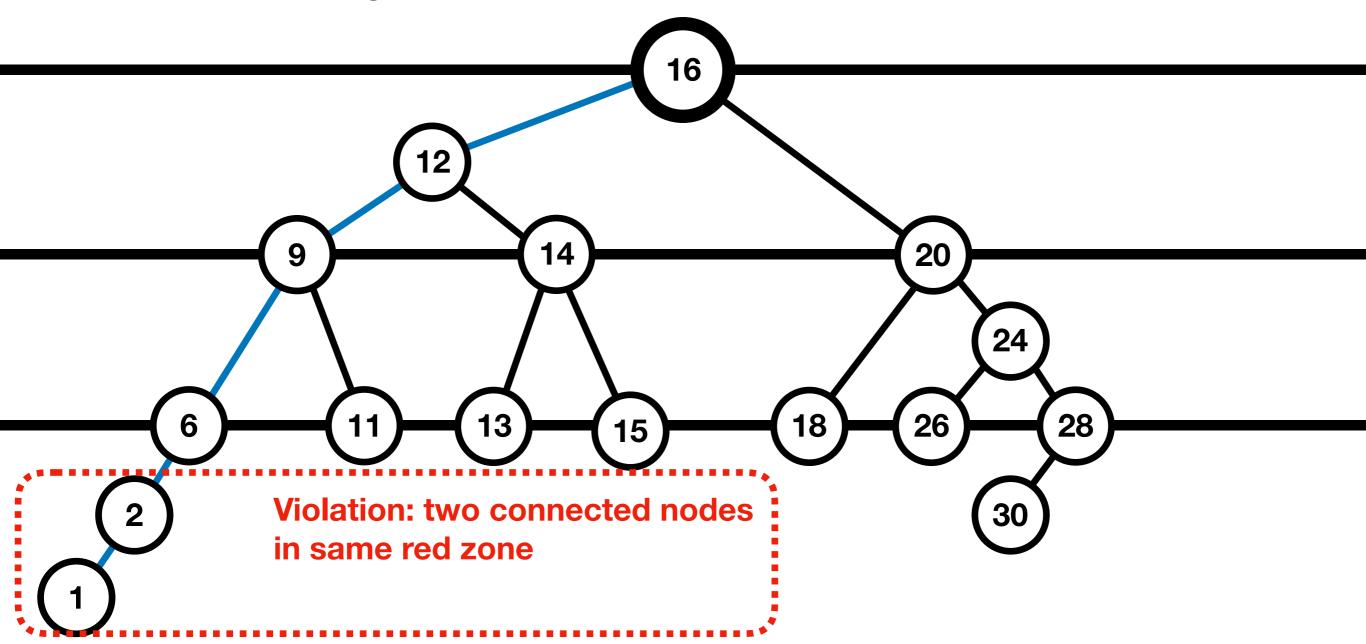
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1. Insert as for ordinary binary search tree.



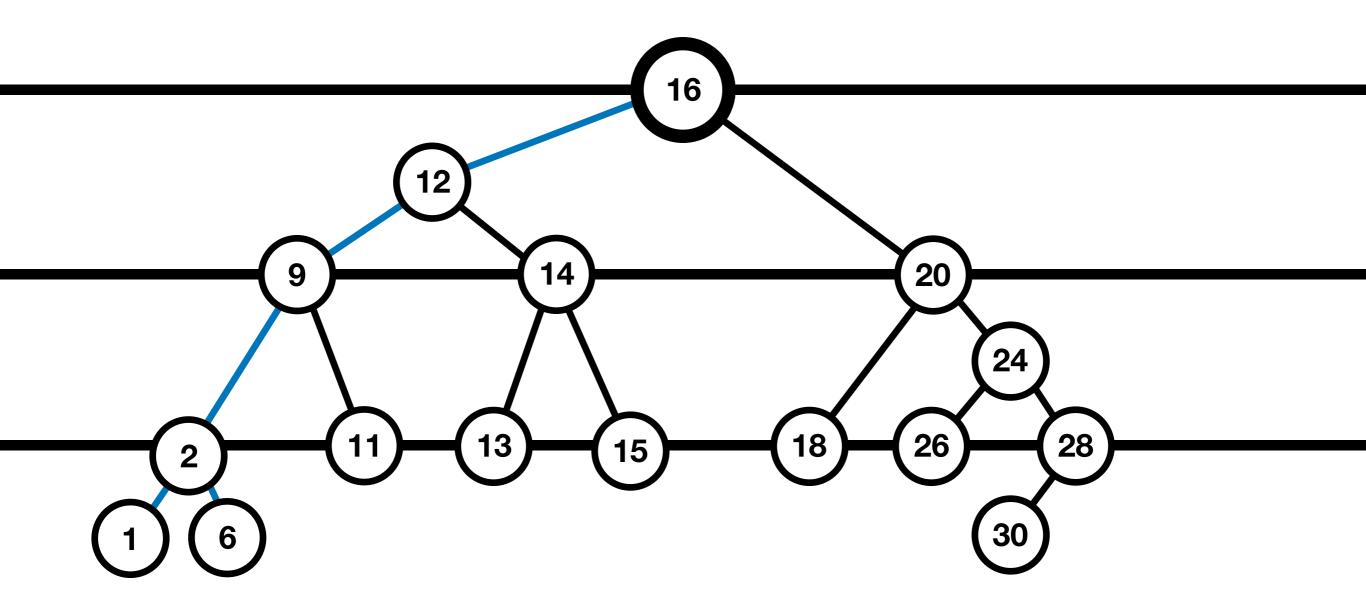
1. Insert as for ordinary binary search tree.

This might cause a temporary violation of rule 4!



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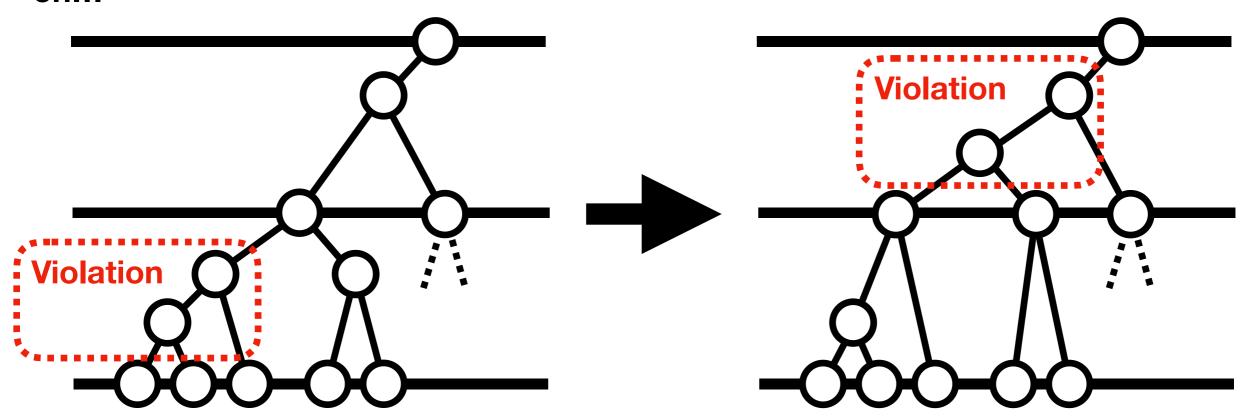
- 1. Insert as for ordinary binary search tree.
- 2. Follow insertion path from bottom up to fix rule violation.



### Fixing the rule violation

The previous example was easy, just one "right-rotation".

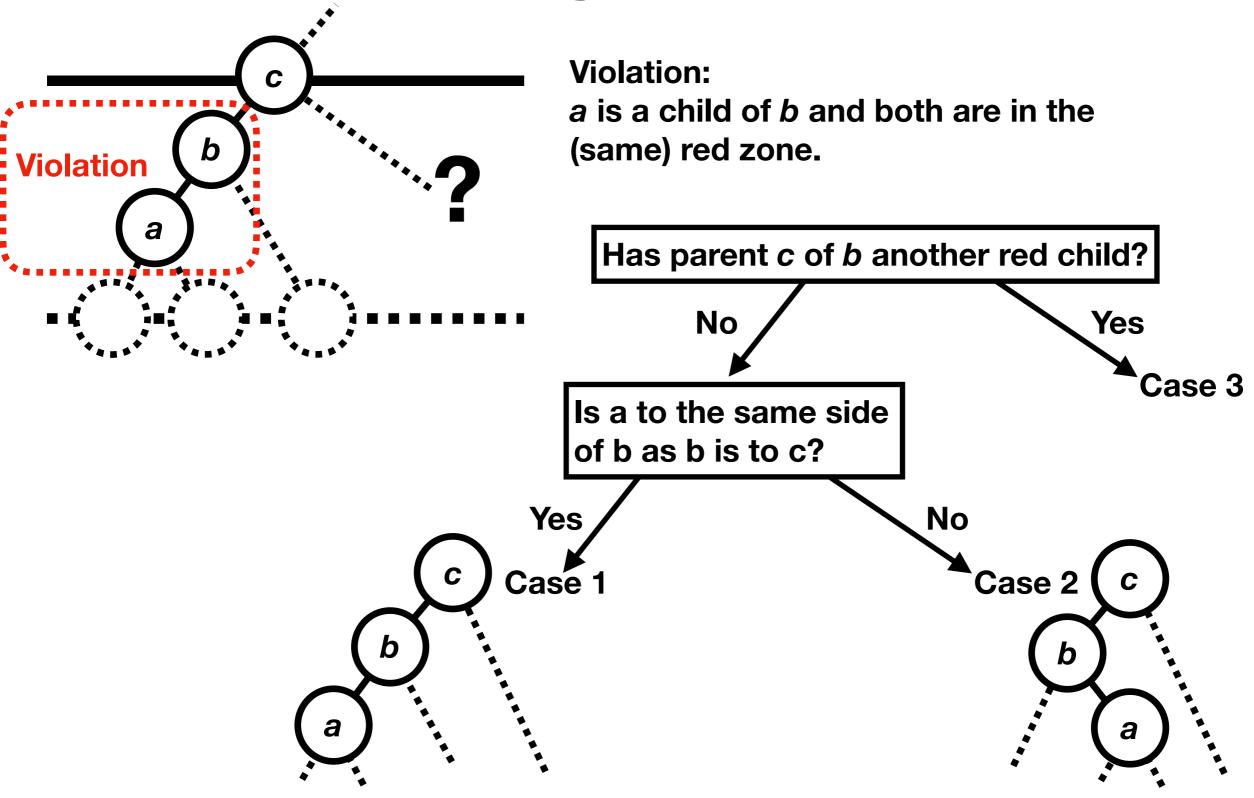
In general, while fixing a violation in one red zone, we might introduce another violation in the zone above which we then need to fix and so on...



... until we hit the root. A that point, we can fix the tree by changing the root or moving it half a grid line up.

This might sound complicated, but it really boils down to: only 3 cases (up to mirroring)!

### Case analysis: overview



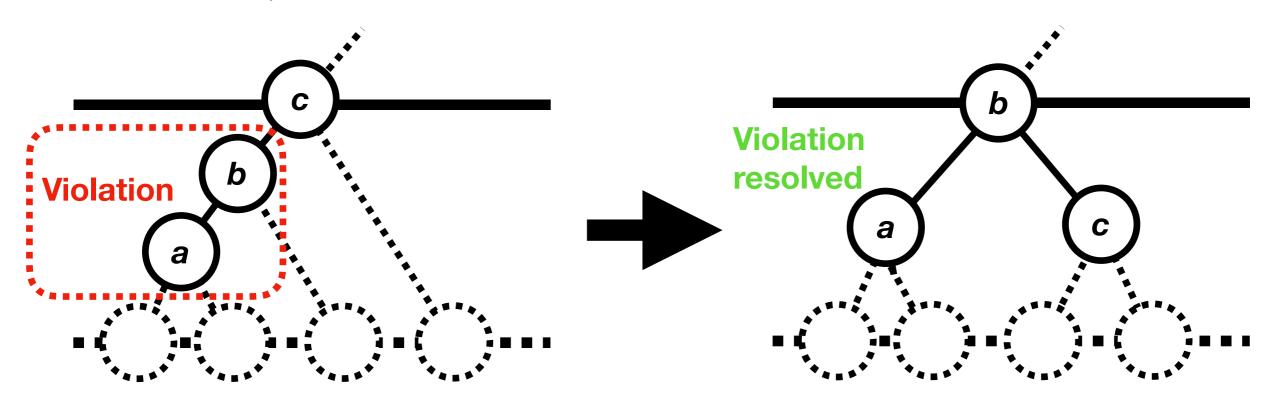
### Case 1

#### A node b in a red zone

- has a left child a in the (same) red zone and
- is the left child of a node c and c has no right child in the red zone.

#### **Resolution:**

- Right-rotate about c.
- If c was a root, set b as new root.



Note that this works the same when the red zone is the lowest one and when interchanging left and right everywhere.

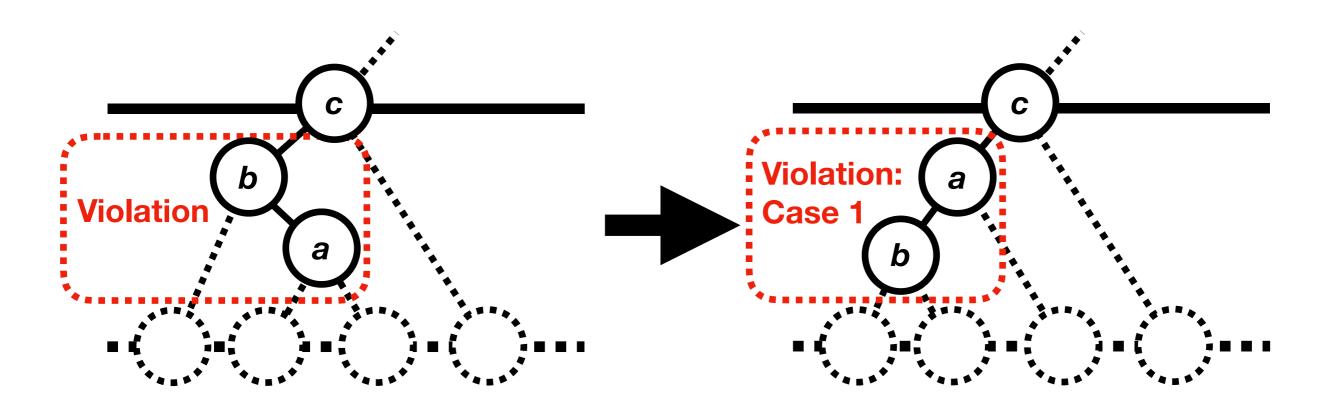
### Case 2

#### A node b in a red zone

- has a right child a in the (same) red zone and
- is the left child of a node c and c has no right child in the red zone.

#### **Resolution:**

Left-rotate about b to reduce to case 1.



Note that this works the same when the red zone is the lowest one and when interchanging left and right everywhere.

### Case 3

#### A node b in a red zone

- has a child a in the (same) red zone and
- its parent c has two children in the red zone, call the other one d.

#### **Resolution:**

Move b, c, and d half a gridline up.

Check whether c has a parent in the red zone (that c is now in), if

yes apply appropriate case to fix new violation.

If c was the root, ...

Potential violation

Violation

a

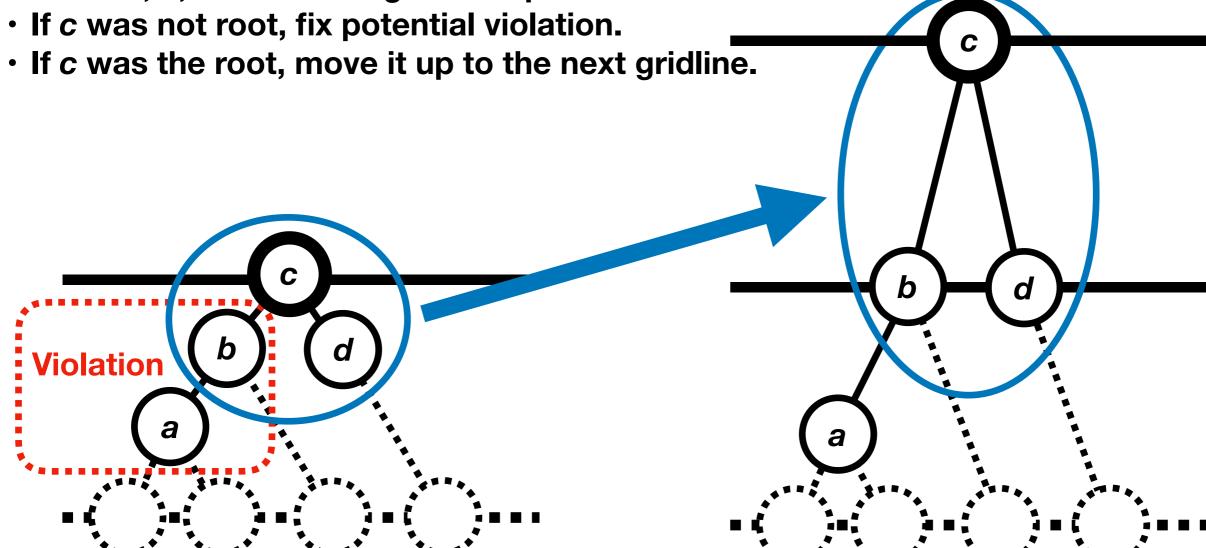
### Case 3: root

#### A node b in a red zone

- has a child a in the (same) red zone and
- its parent c has two children in the red zone, call the other one d.

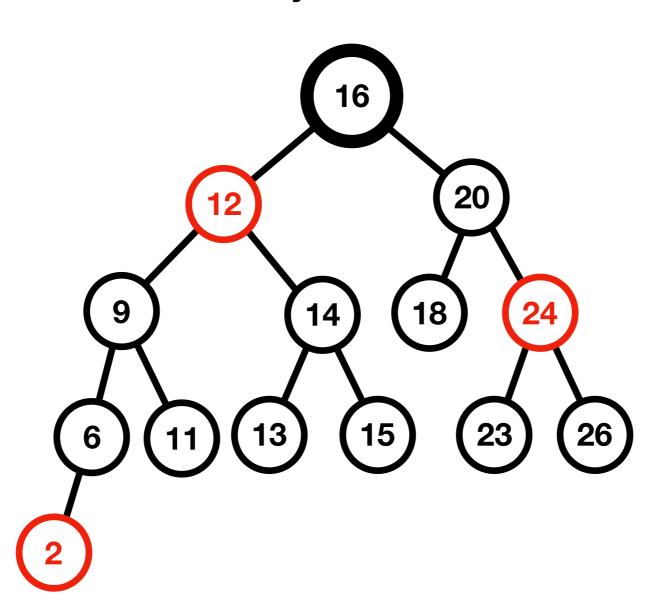
#### **Resolution:**

Move b, c, and d half a gridline up.



### Implementation

Two-colored binary search tree



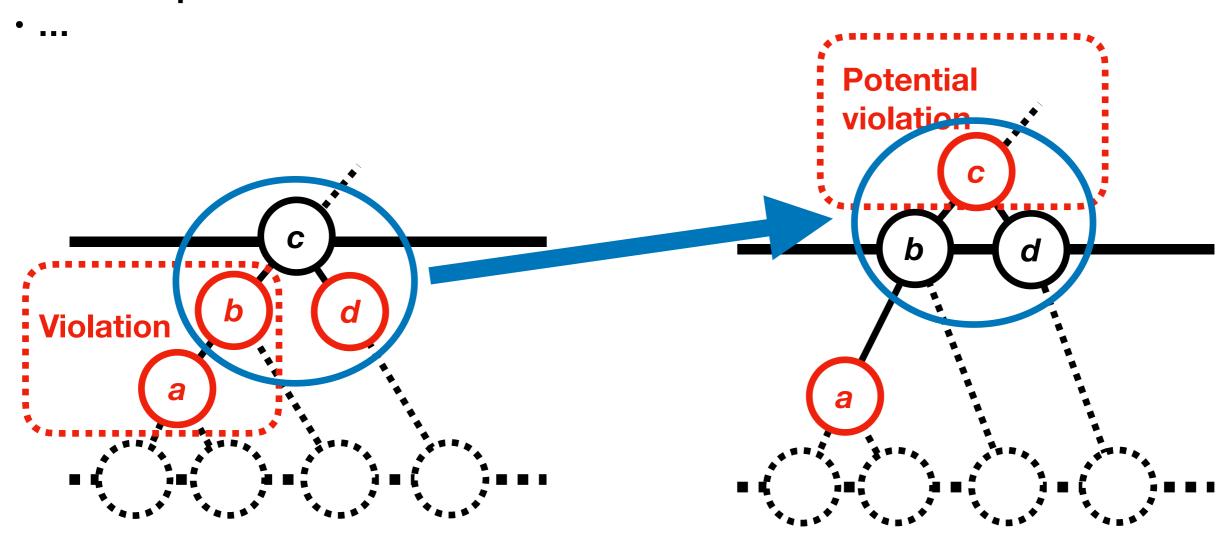
### Case 3 graphically

#### A node b in a red zone

- has a child a in the (same) red zone and
- its parent c has two children in the red zone, call the other one d.

#### Resolution (graphically):

- Move b and d up to the next gridline
- Move c up to the next red zone



### Implementation of Case 3

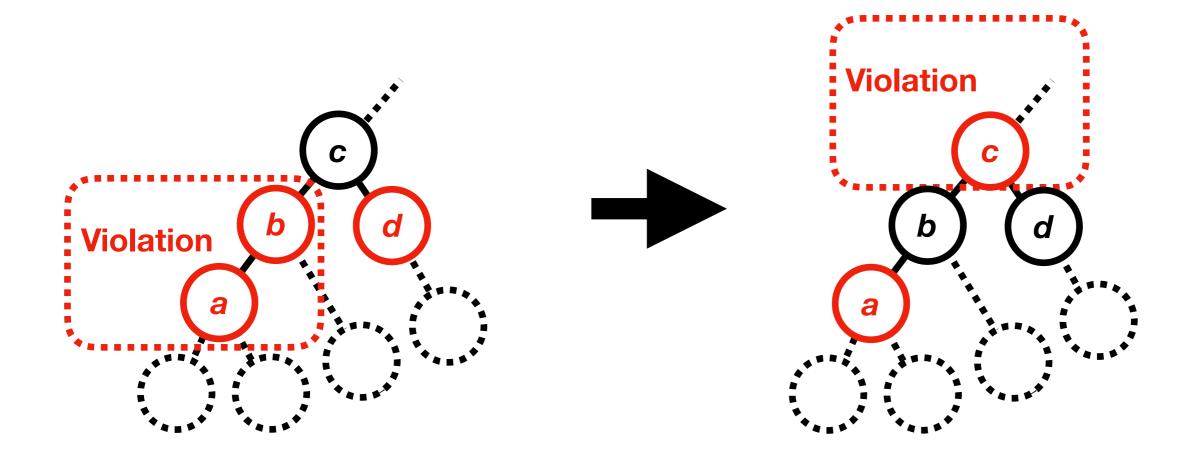
#### A node b is red and

- has a red child a and
- its parent c has two red children, call the other one d.

#### Resolution (implementation):

- Color b and d black (to indicate gridline)
- Color c red (to indicate red zone)

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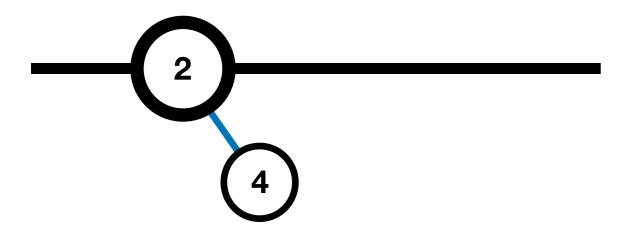
Adding 2 as root to empty tree.

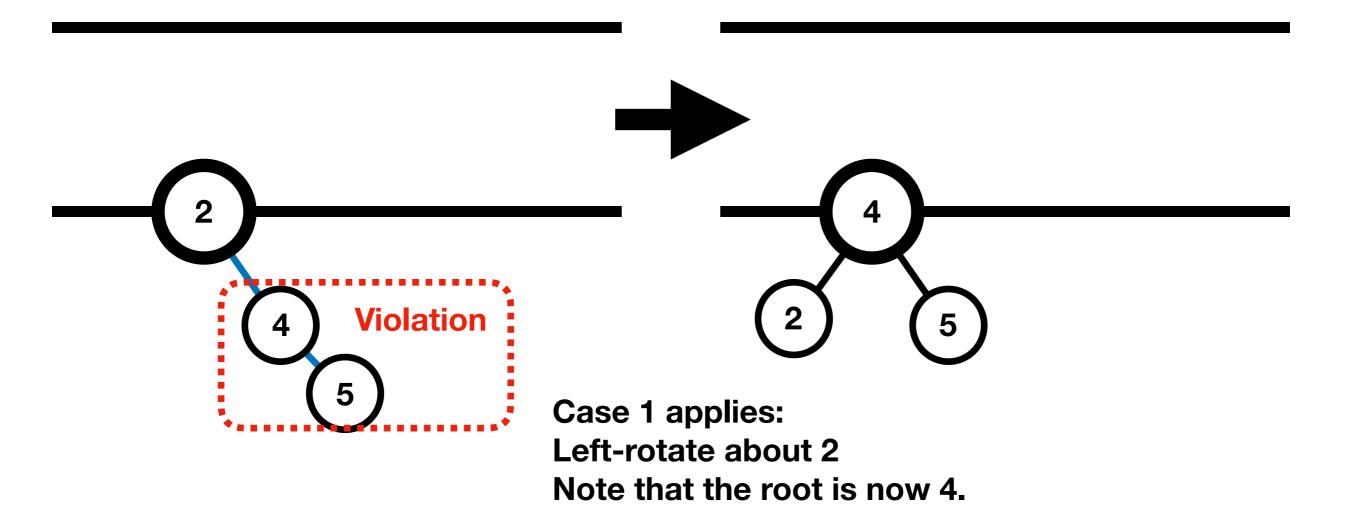
No fix required.

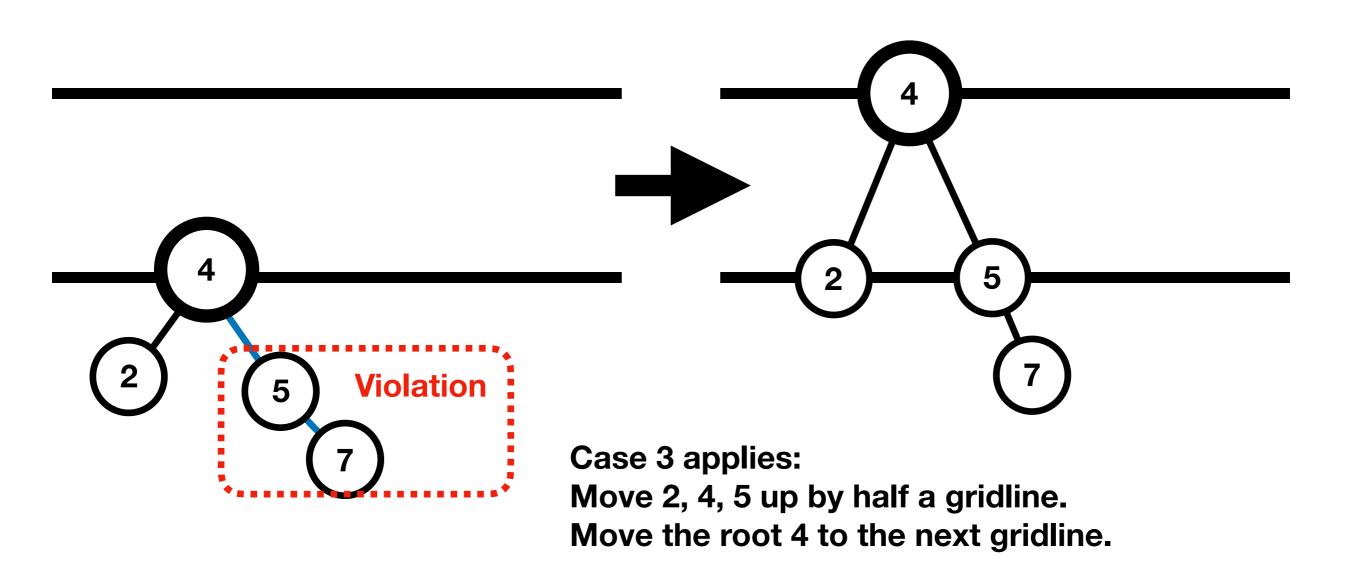


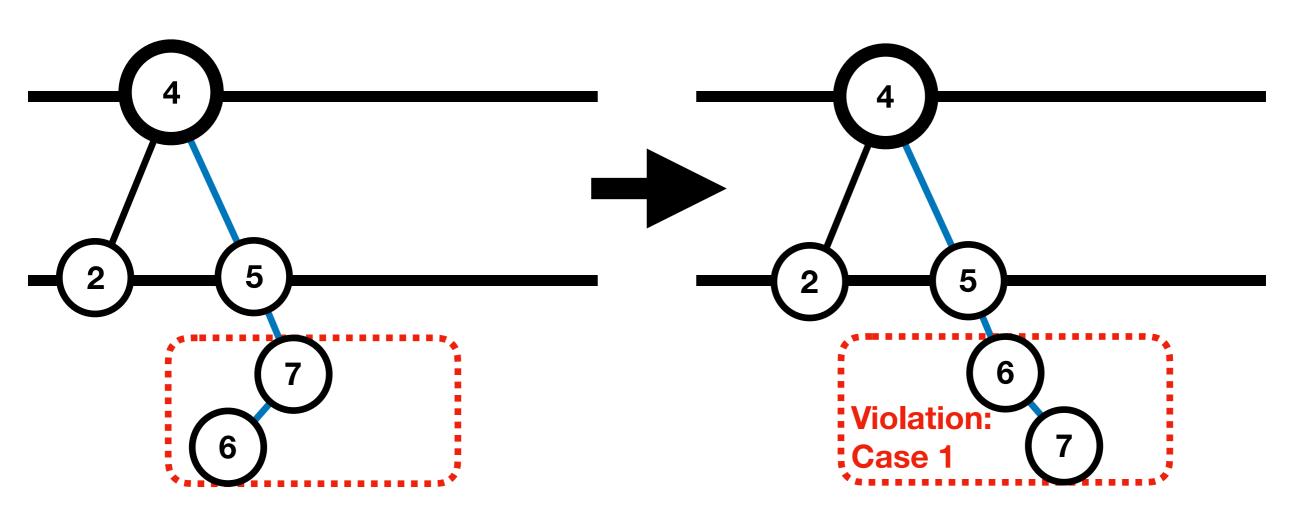
Starting with tree having only one node, insert 4.

No fix required.



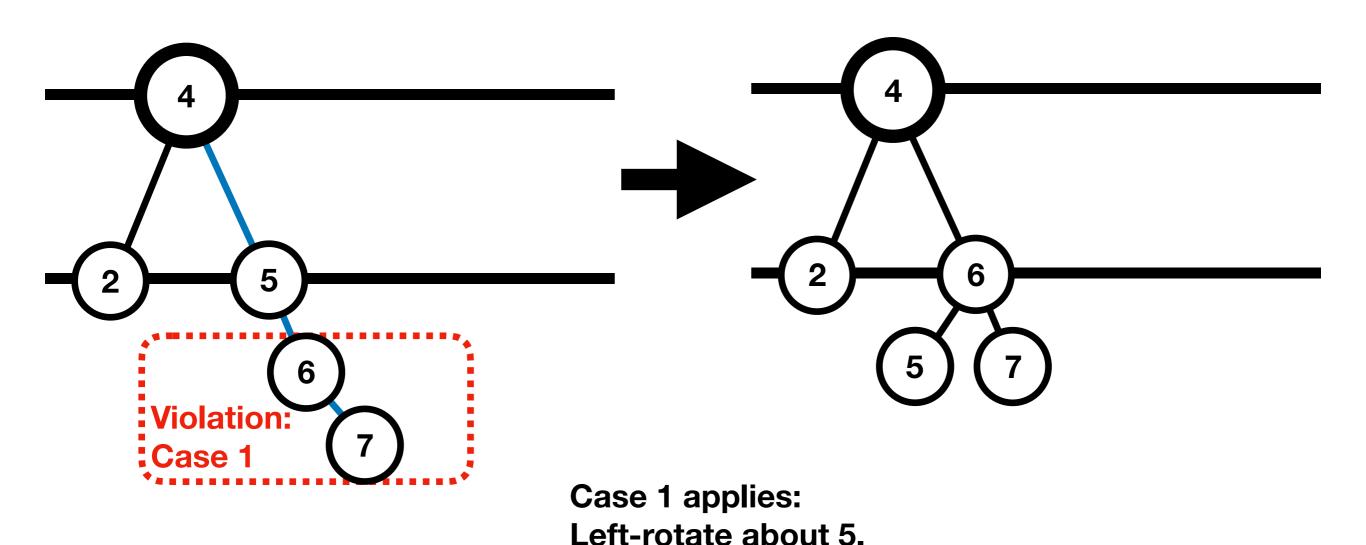


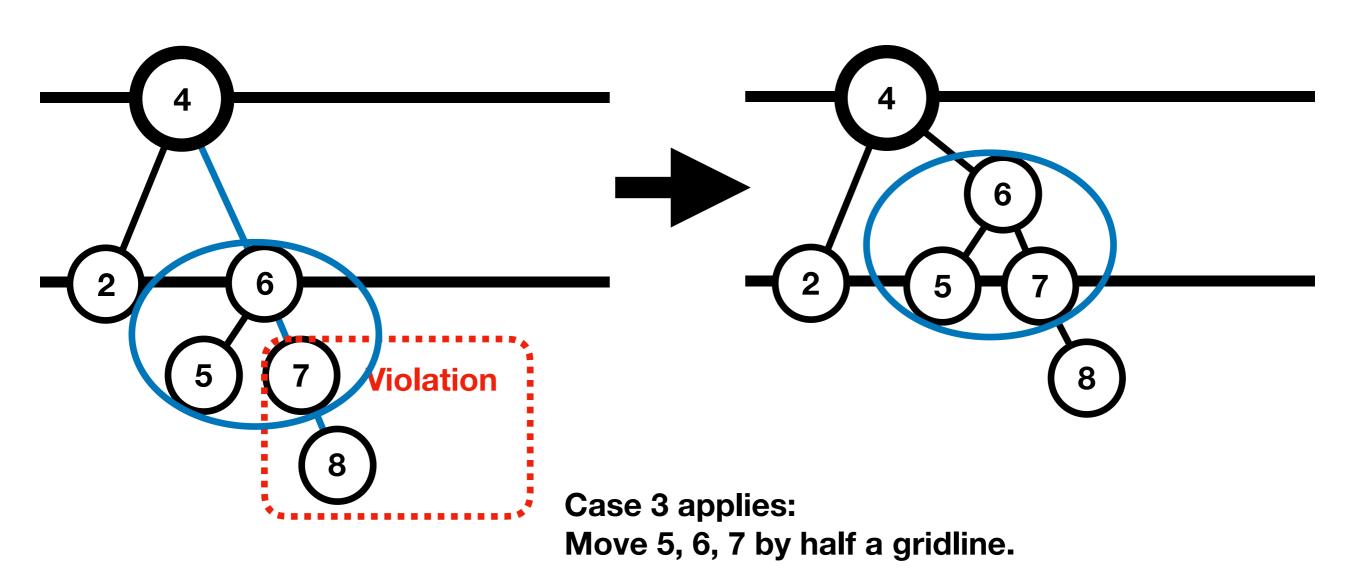


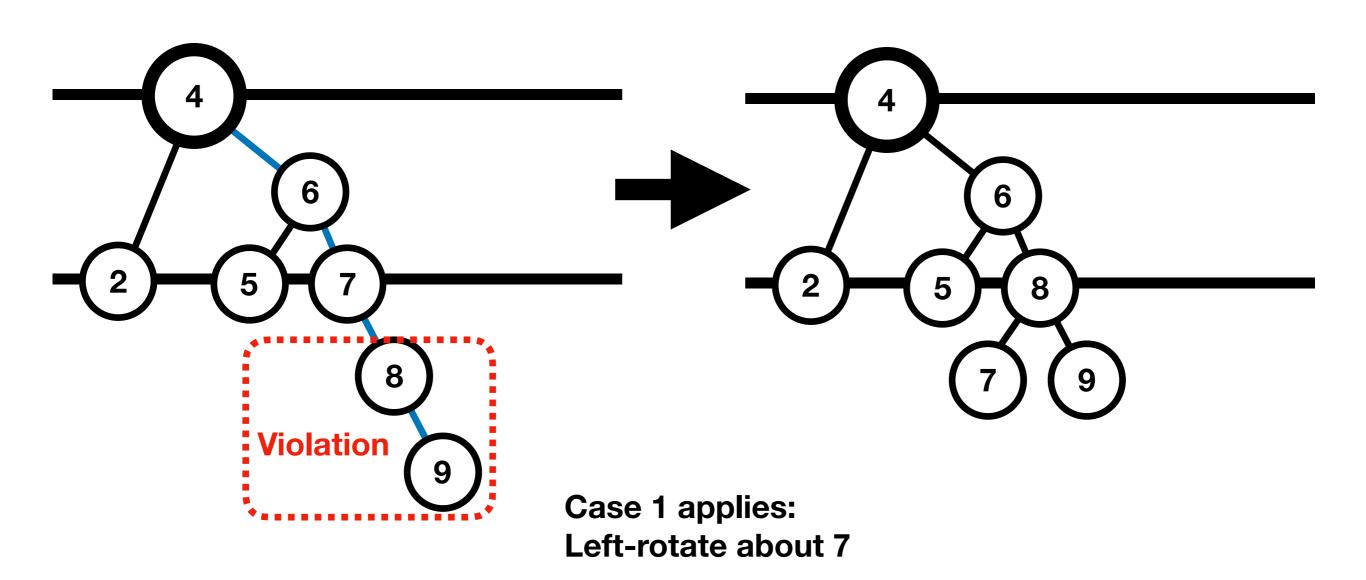


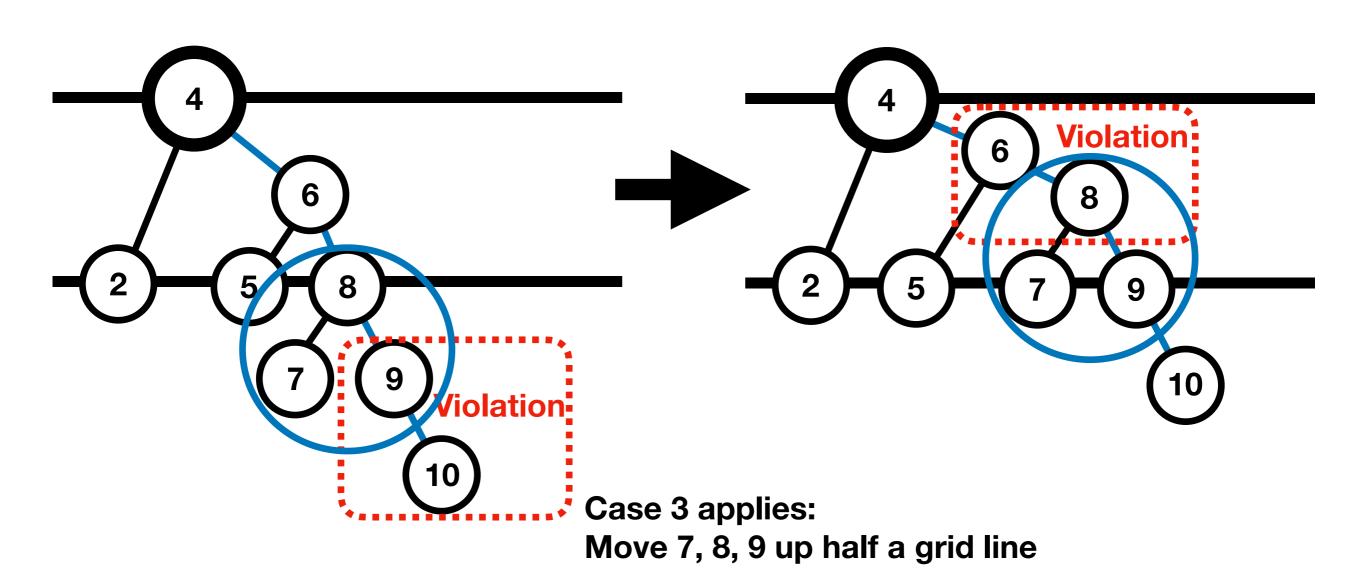
Case 2 applies: Right-rotate about 7 to reduce to case 1.

### Example: Insert 6 (part 2)









### Example: Insert 10 (part 2)

